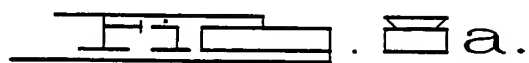
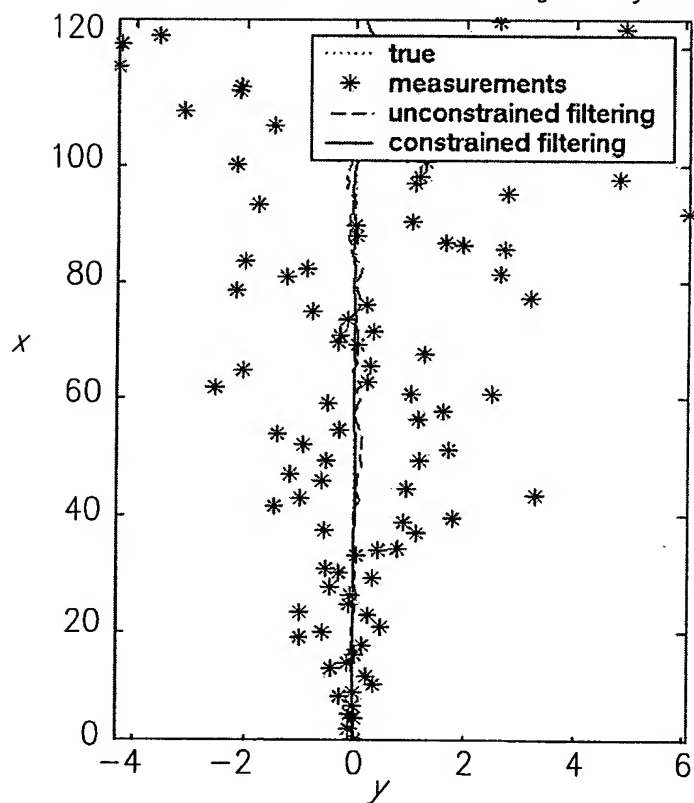
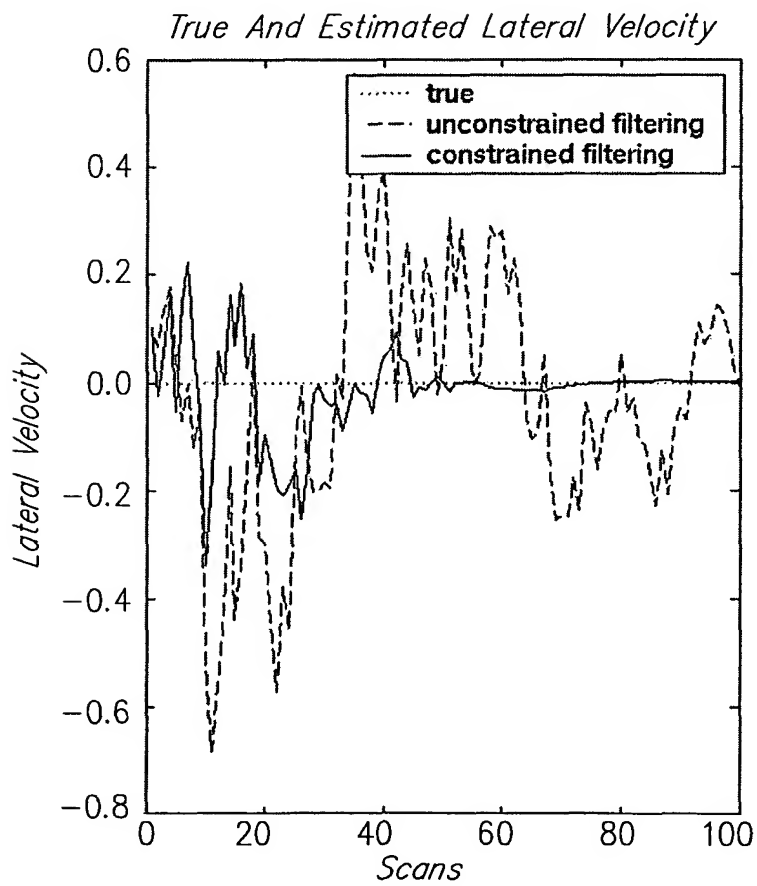
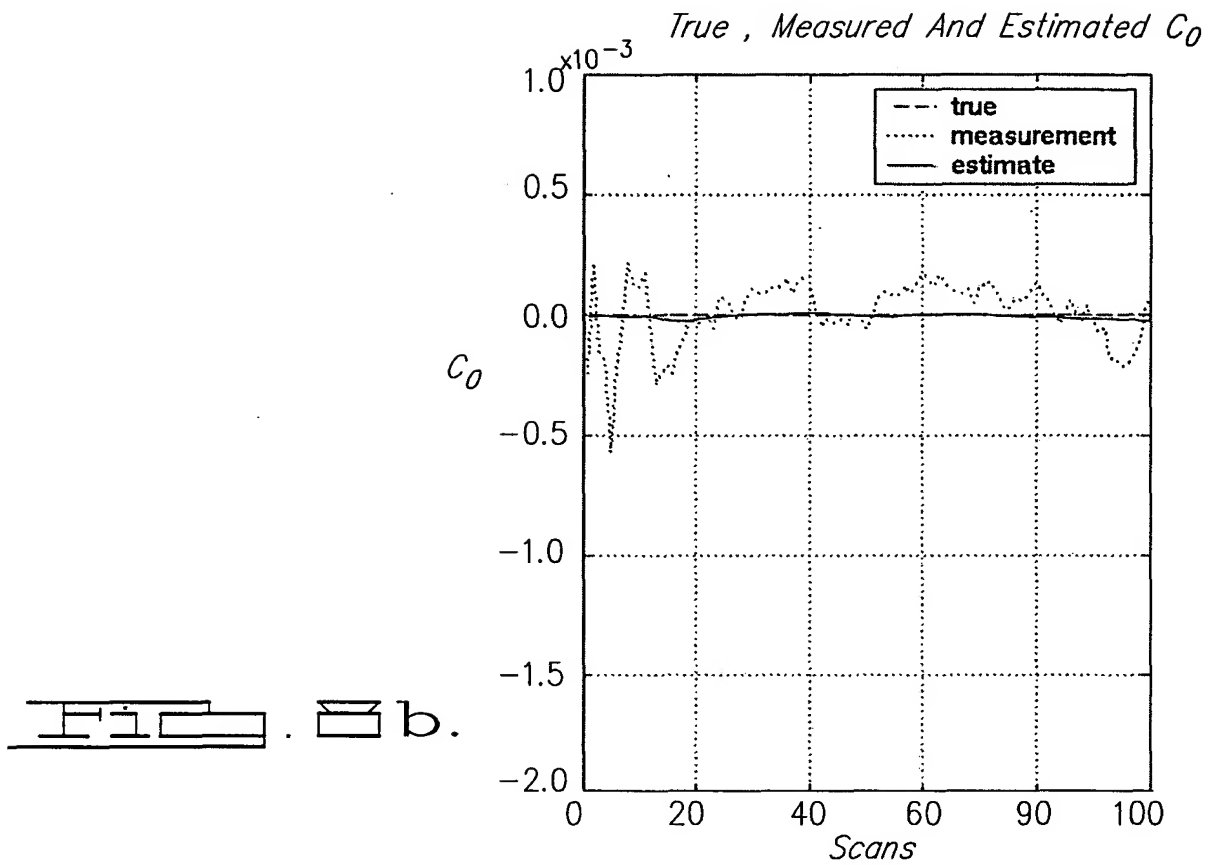


True, Measured & Estimated Target Trajectory





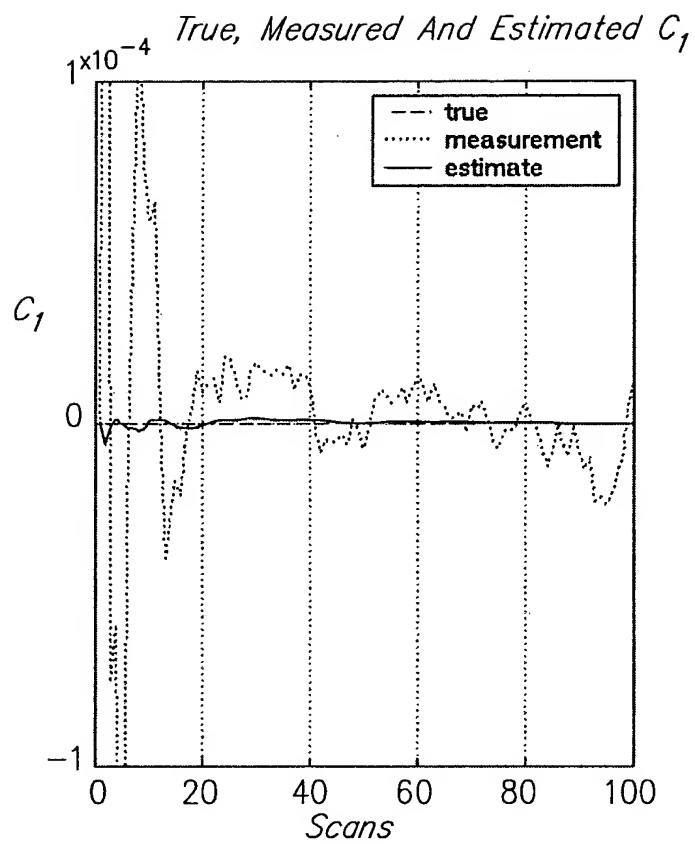


Figure 8d.

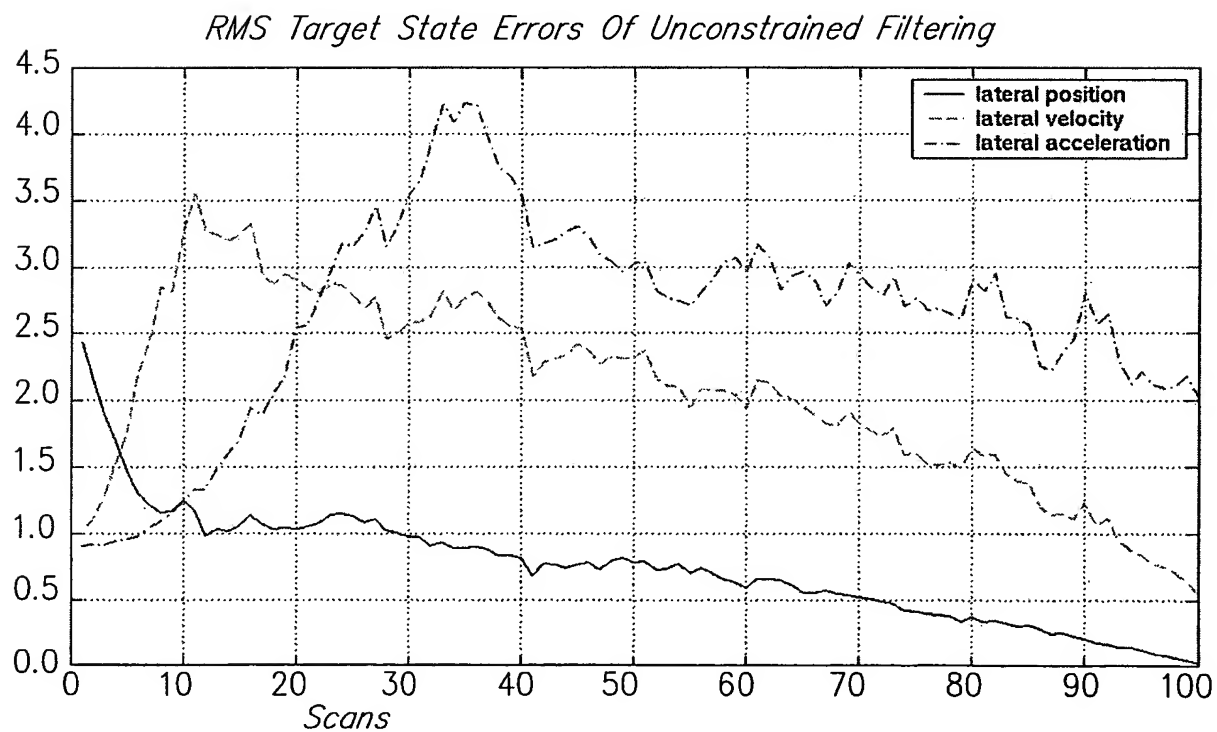


Figure 9a.

*RMS Target State Errors Of Constrained Filtering*

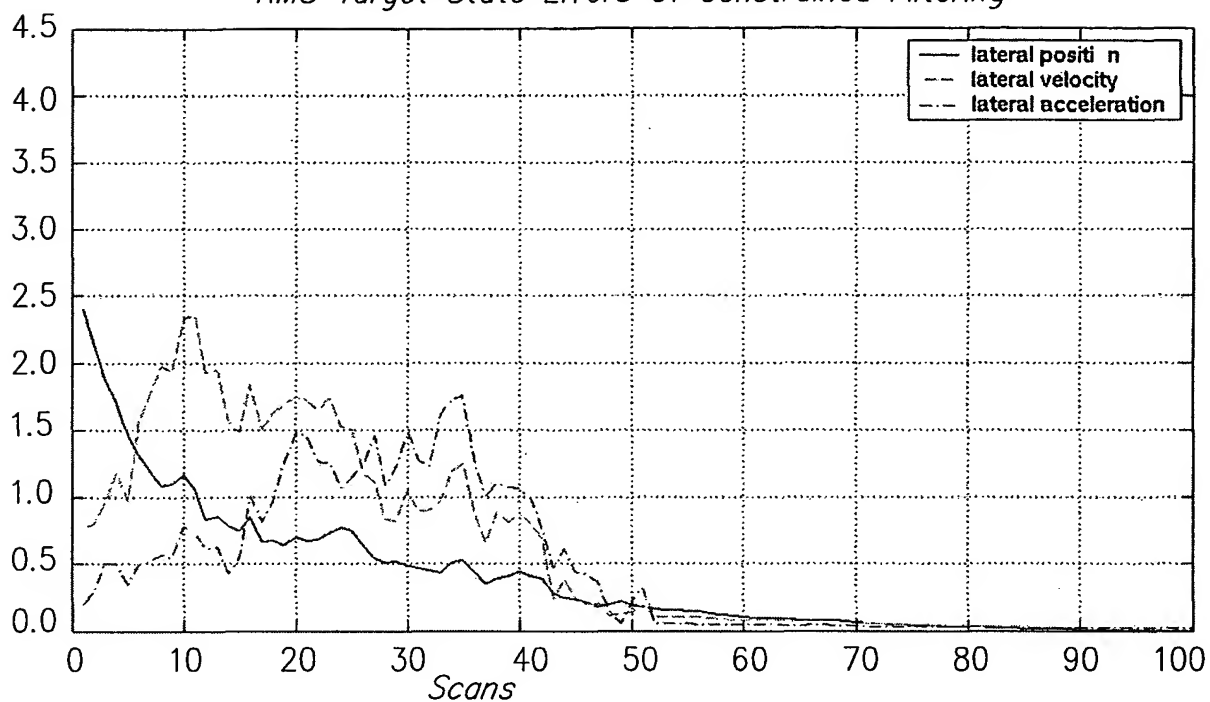


Figure 1b.

*True, Measured & Estimated Target Trajectory*

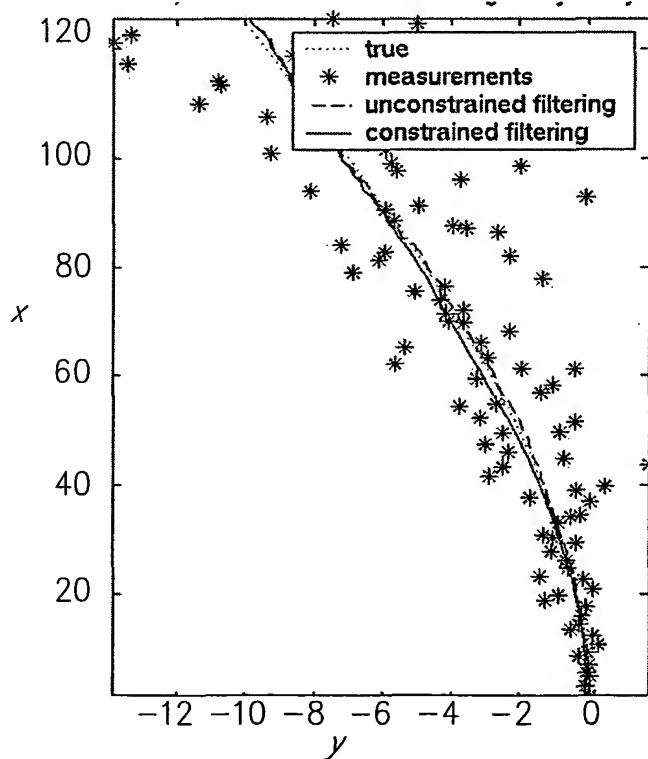


Figure 1a.

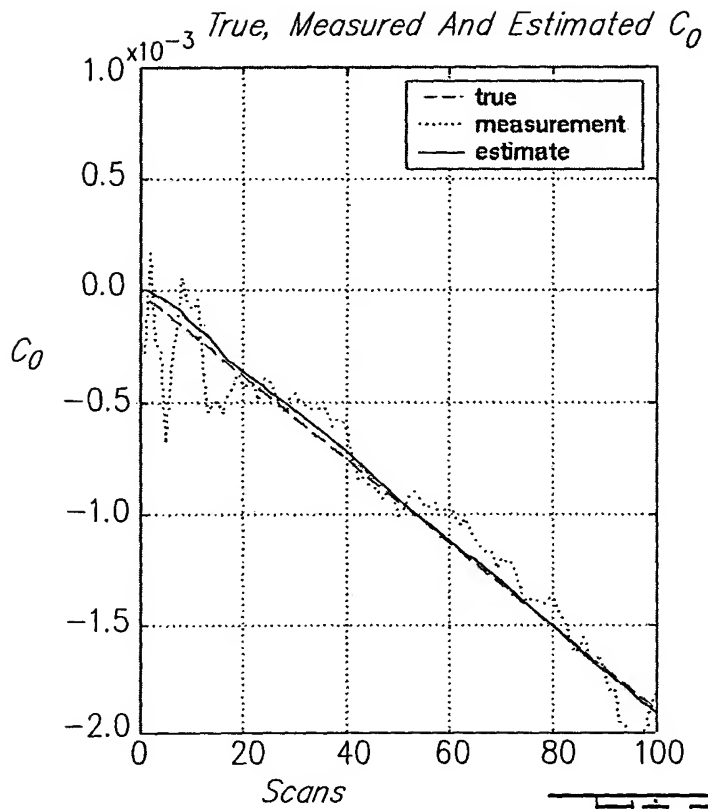


Fig. 1 □ b.

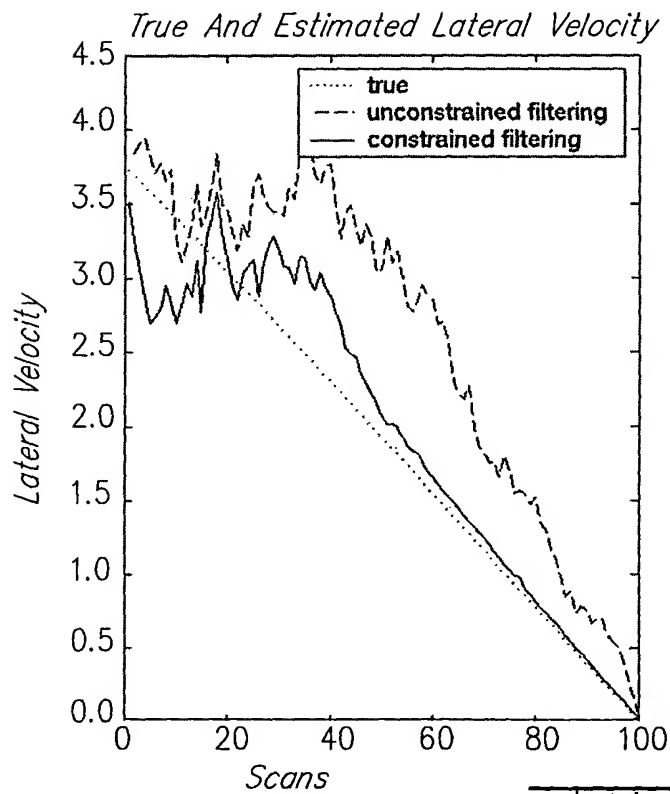


Fig. 1 □ c.



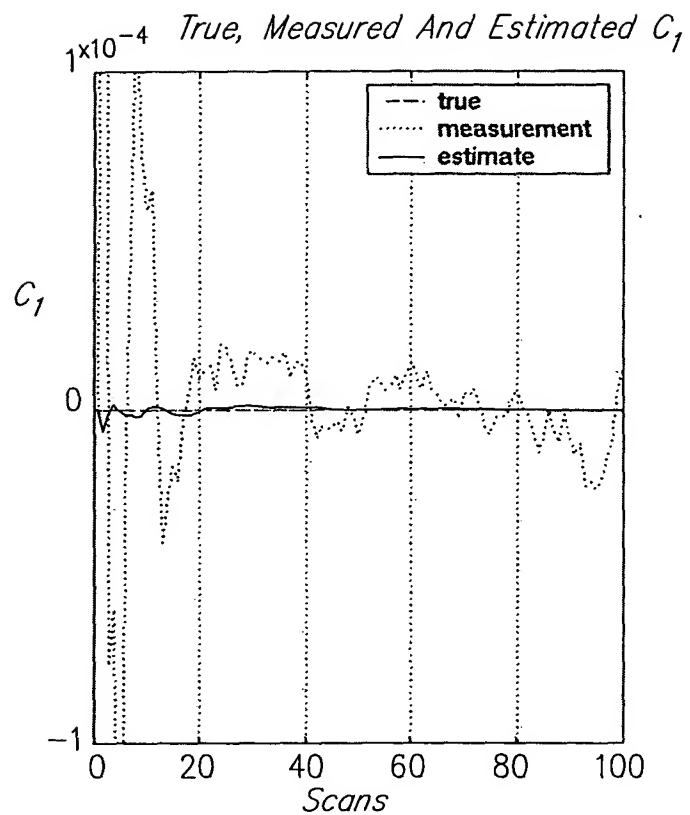


Fig. 1 d.

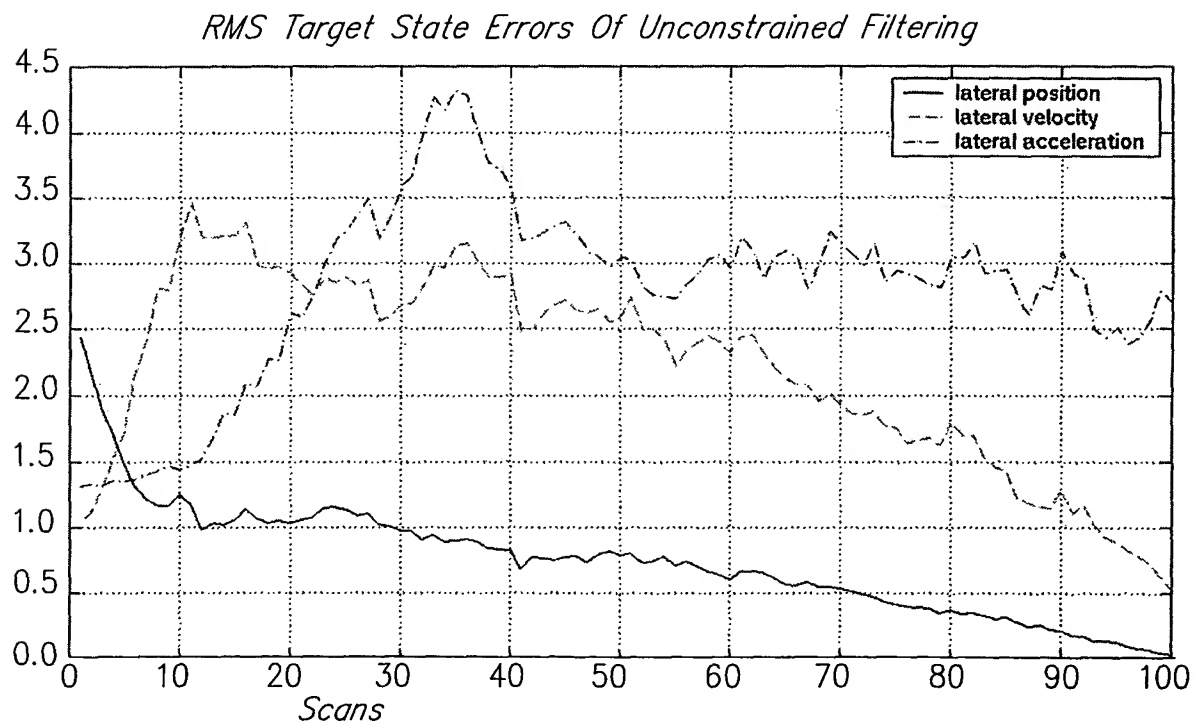


Fig. 1 1 a.

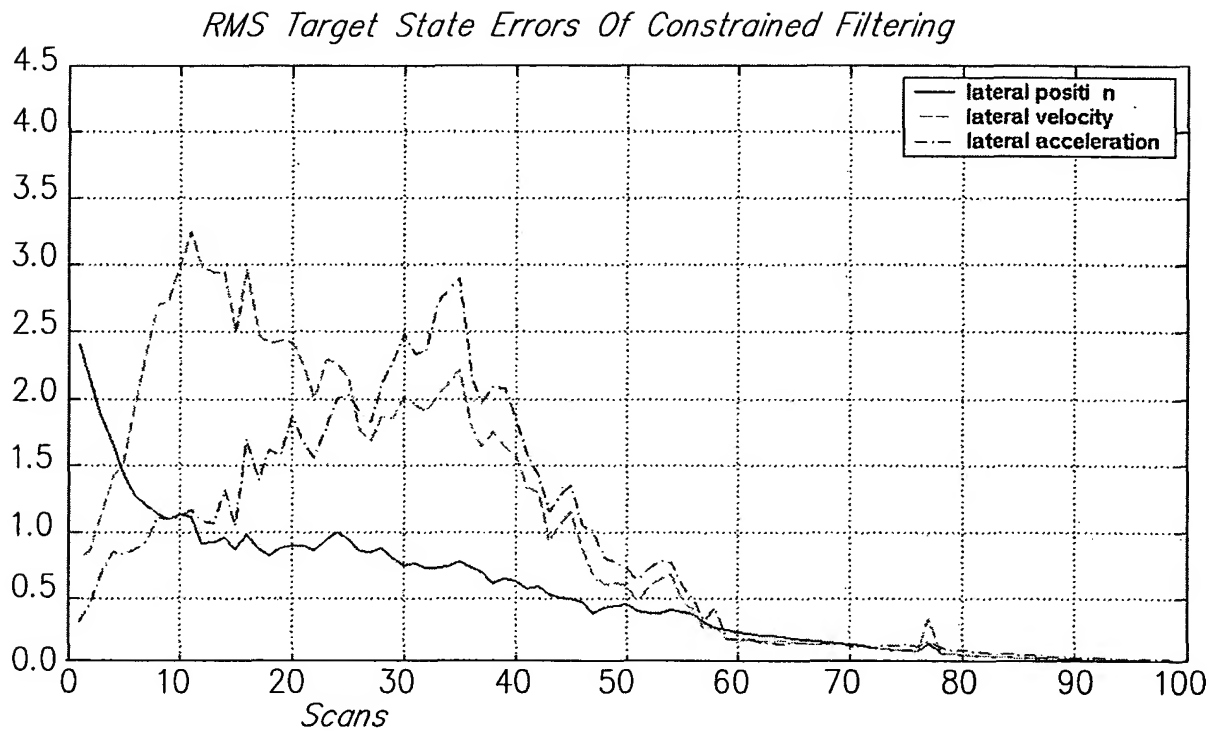


Fig. 11b.

*True, Measured & Estimated Target Trajectory*

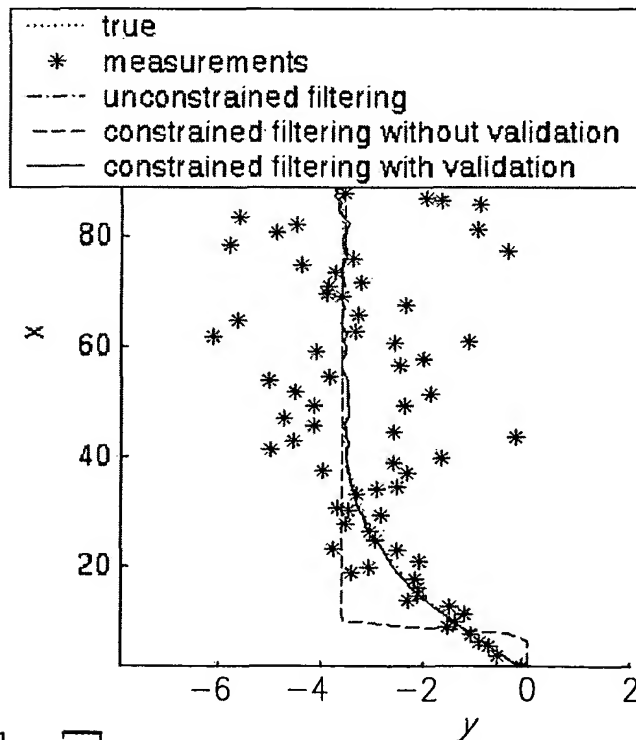


Fig. 11a.

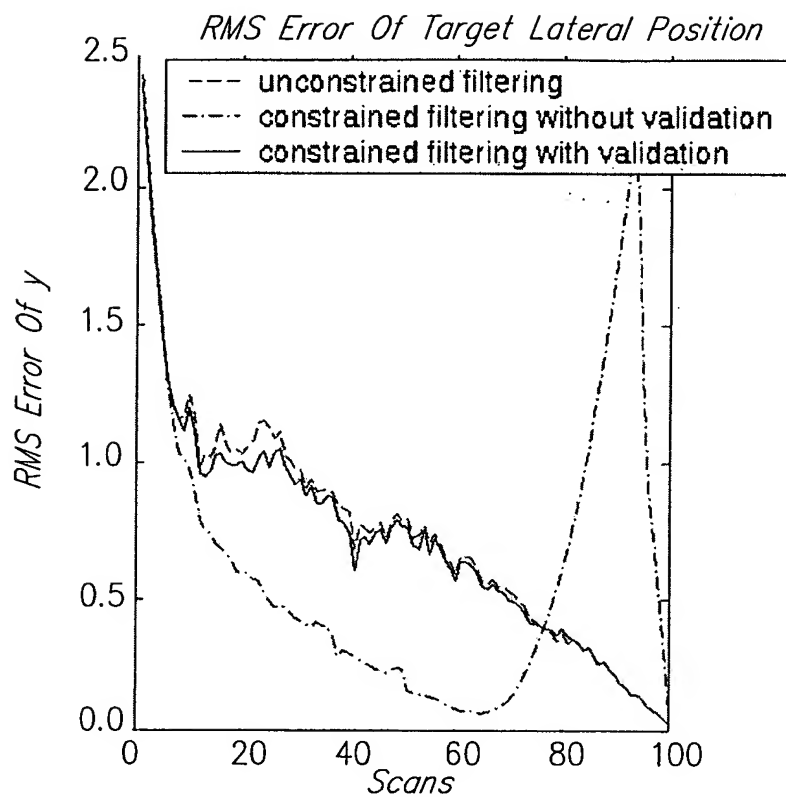


Figure 12b.

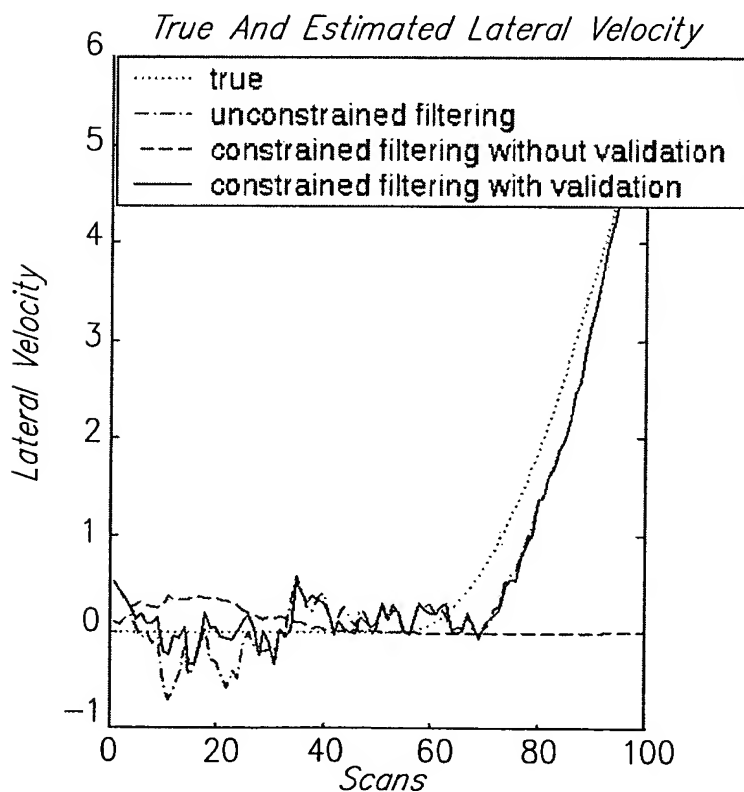


Figure 12c.

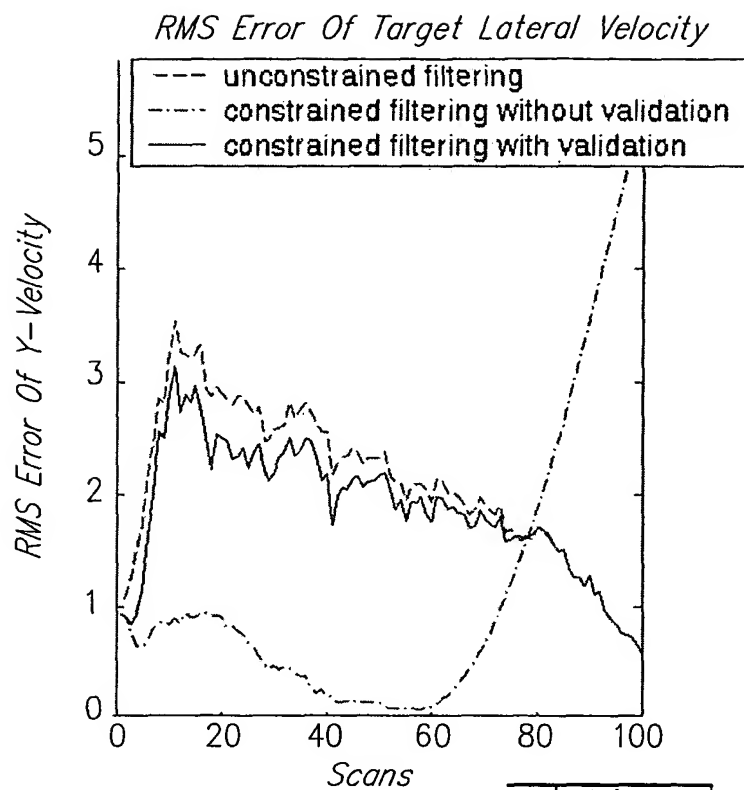


Figure 12d.

*True, Measured & Estimated Target Trajectory*

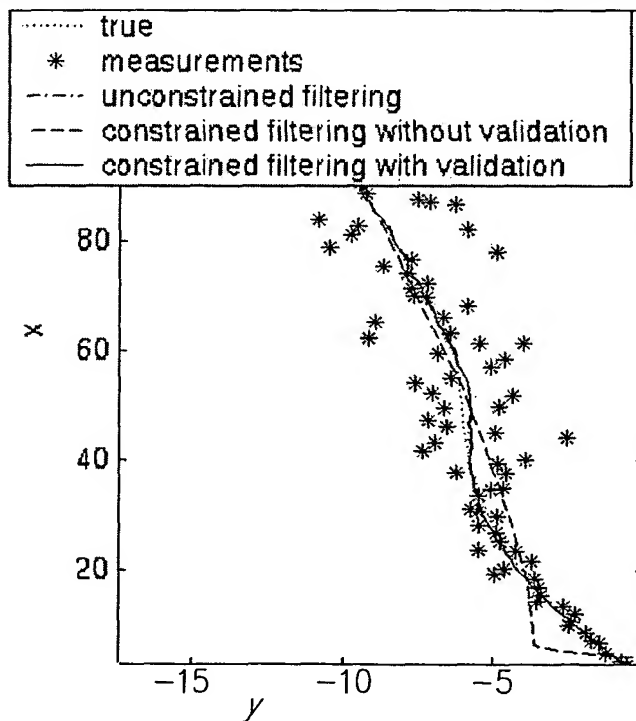


Figure 13a.

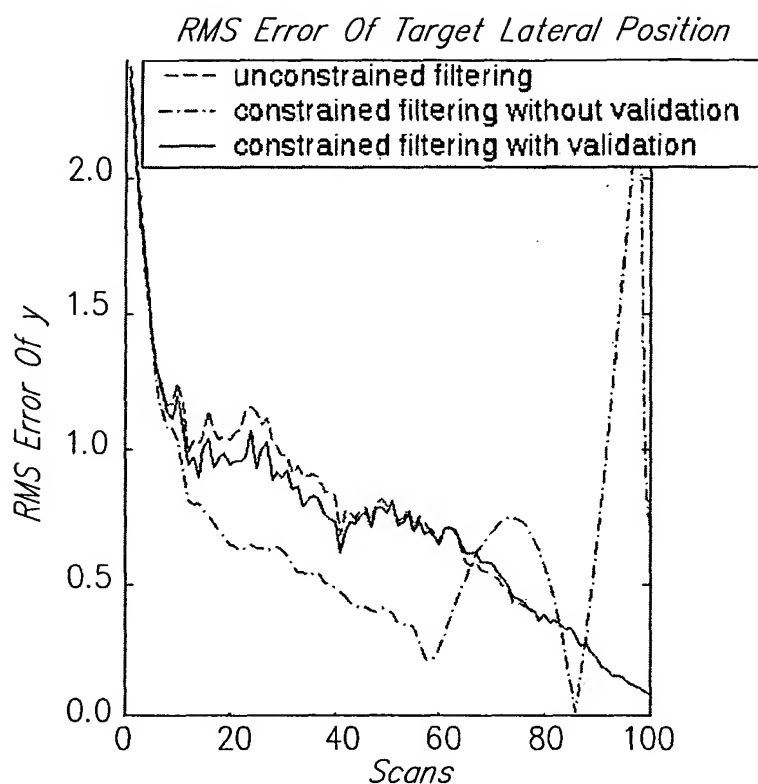


Fig. 13b.

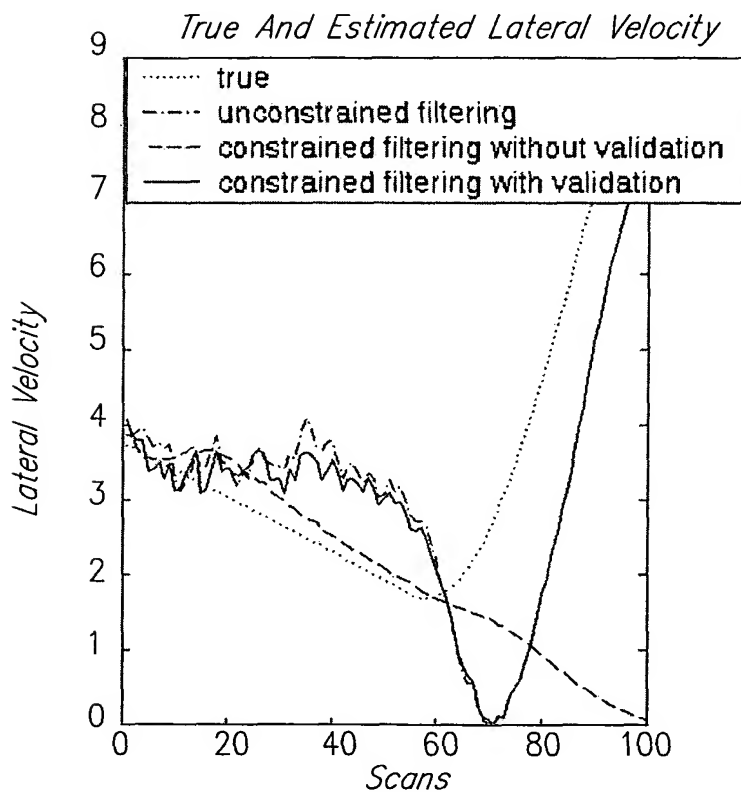


Fig. 13c.

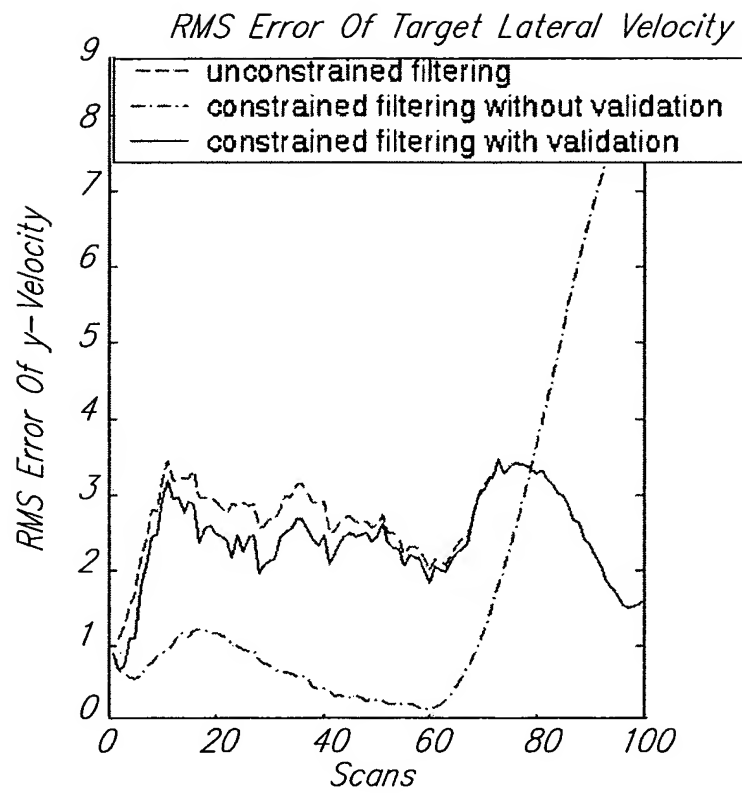


Fig. 13d.